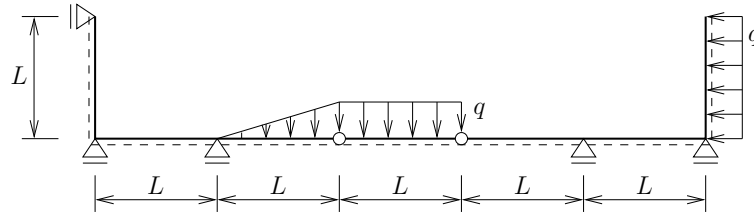
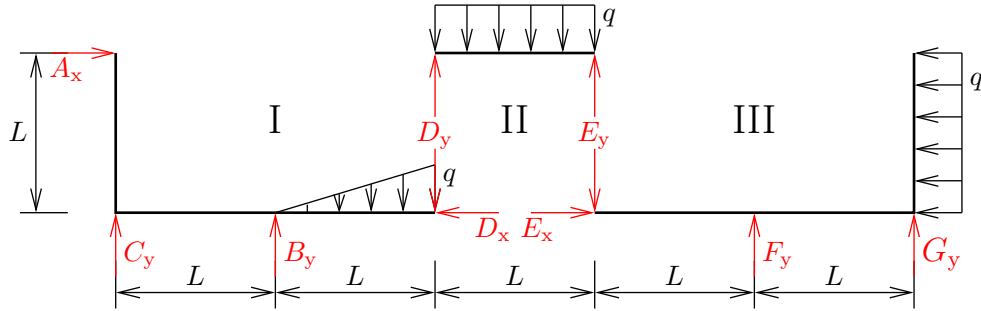


Zadání: Vyjádřete a vykreslete funkce průběhů vnitřních sil $N(x)$, $T(x)$, $M(x)$ na daném nosníku.



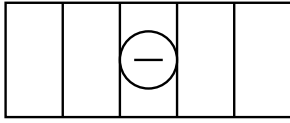
Reakce v podporách



$$\begin{aligned} \curvearrowright d_{II} : -qL\frac{1}{2}L + E_yL &= 0 \\ E_y &= \frac{1}{2}qL \\ \uparrow y_{II} : D_y - qL + E_y &= 0 \\ D_y - qL + \frac{1}{2}qL &= 0 \\ D_y &= \frac{1}{2}qL \\ \rightarrow x_{II} : D_x - E_x &= 0 \\ D_x &= qL \end{aligned}$$

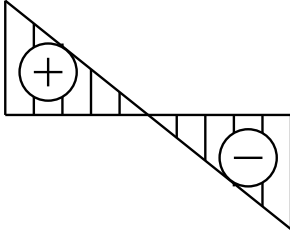
$$\begin{aligned} \rightarrow x_I : A_x - D_x &= 0 & \rightarrow x_{III} : E_x - qL &= 0 \\ A_x &= qL & E_x &= qL \\ \curvearrowright c_I : -A_xL - B_yL - D_yL - \frac{1}{2}qL\frac{2}{3} &= 0 & \curvearrowright f_{III} : E_yL + G_yL + qL\frac{1}{2}L &= 0 \\ -qL^2 - B_yL - \frac{1}{2}qL^2 - \frac{1}{3}qL^2 &= 0 & \frac{1}{2}qL^2 + G_yL\frac{1}{2}qL^2 &= 0 \\ B_y &= -\frac{11}{6}qL & G_y &= -qL \\ \uparrow y_{II} : B_y + C_y - D_y - \frac{1}{2}qL &= 0 & \uparrow y_{III} : -E_y + F_y + G_y &= 0 \\ -\frac{11}{6}qL + C_y - \frac{1}{2}qL - \frac{1}{2}qL &= 0 & -\frac{1}{2}qL + F_y - qL &= 0 \\ C_y &= \frac{17}{6}qL & F_y &= \frac{3}{2}qL \end{aligned}$$

pole II



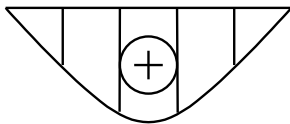
průběh normálových sil

$$\begin{aligned} x \in \langle d, e \rangle : N(x) &= -D_x = -qL \\ N(d) &= -qL \\ N(e) &= -qL \end{aligned}$$



průběh posouvajících sil

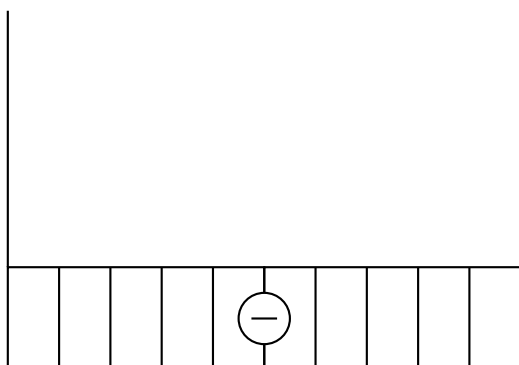
$$\begin{aligned} x \in \langle d, e \rangle : T(x) &= -D_y - qx \\ &= \frac{1}{2}gL - qx \\ T(d) &= \frac{1}{2}qL \\ T(e) &= -\frac{1}{2}qL \\ T(x_{M_{max}}) &= 0 = \frac{1}{2}qL - qx_{M_{max}} \\ x_{M_{max}} &= \frac{1}{2}L \end{aligned}$$



průběh ohybových momentů

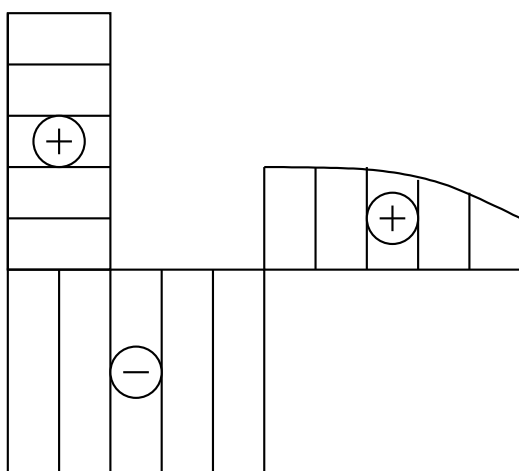
$$\begin{aligned} x \in \langle d, e \rangle : M(x) &= -D_y x - qx \frac{1}{2}x \\ &= \frac{1}{2}qLx - \frac{1}{2}qx^2 \\ M(d) &= 0 \\ M(e) &= 0 \\ M(max) &= \frac{1}{4}qL^2 - \frac{1}{8}qL^2 = \frac{1}{8}qL^2 \end{aligned}$$

pole I



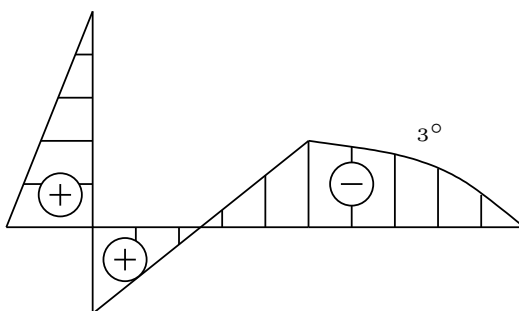
průběh normálových sil

$$\begin{aligned}
 x \in \langle a, b \rangle : N(x) &= 0 \\
 N(a) &= 0 \\
 N(b) &= 0 \\
 x \in \langle b, c \rangle : N(x) &= -A_x \\
 N(b) &= -qL \\
 N(c) &= -gL \\
 x \in \langle d, c \rangle : N(x) &= -D_x \\
 N(d) &= -qL \\
 N(c) &= -gL
 \end{aligned}$$



průběh posouvajících sil

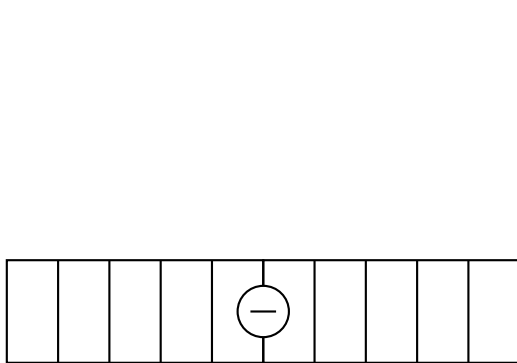
$$\begin{aligned}
 x \in \langle a, b \rangle : T(x) &= A_x = qL \\
 T(a) &= qL \\
 T(b) &= qL \\
 x \in \langle b, c \rangle : T(x) &= -B_y = -\frac{11}{6}qL \\
 T(b) &= -\frac{11}{6}qL \\
 T(c) &= -\frac{11}{6}qL \\
 x \in \langle d, c \rangle : T(x) &= D_y + qx - \frac{1}{2}x\frac{q}{L}x \\
 &= \frac{1}{2}qL + qx - \frac{1}{2}\frac{q}{L}x^2 \\
 T(d) &= \frac{1}{2}qL \\
 T(c) &= \frac{1}{2}qL + qL - \frac{1}{2}\frac{q}{L}L^2 = qL
 \end{aligned}$$



průběh ohybových momentů

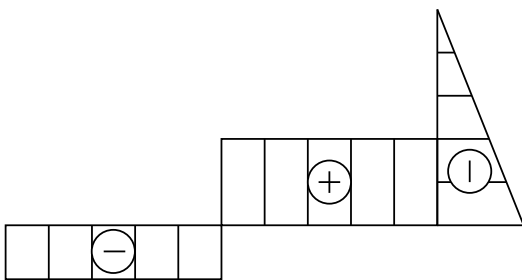
$$\begin{aligned}
 x \in \langle a, b \rangle : M(x) &= A_x x = qLx \\
 M(a) &= 0 \\
 M(b) &= qL^2 \\
 x \in \langle b, c \rangle : M(x) &= M(b) - B_y x = qL^2 - \frac{11}{6}qLx \\
 M(b) &= qL^2 \\
 M(c) &= qL^2 - \frac{11}{6}qL^2 = -\frac{5}{6}qL^2 \\
 x \in \langle d, c \rangle : M(x) &= -D_y x - qx\frac{1}{2}x + \frac{12x}{L}x\frac{1}{3}x \\
 &= -\frac{1}{2}qLx - \frac{1}{2}qx^2 + \frac{1}{6}\frac{q}{L}x^3 \\
 M(d) &= 0 \\
 M(c) &= -\frac{1}{2}qL^2 - \frac{1}{2}qL^2 + \frac{1}{6}\frac{q}{L}L^3 = -\frac{5}{6}qL^2
 \end{aligned}$$

pole III



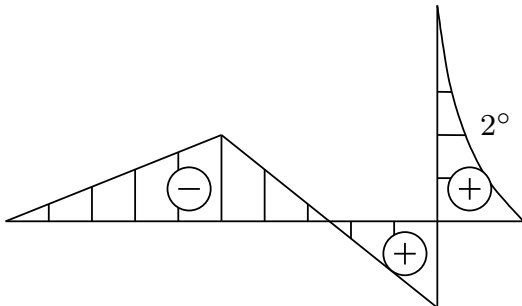
průběh normálových sil

$$\begin{aligned}
 x \in \langle h, g \rangle : N(x) &= 0 \\
 N(h) &= 0 \\
 N(g) &= 0 \\
 x \in \langle g, f \rangle : N(x) &= -gL \\
 N(g) &= -qL \\
 N(f) &= -gL \\
 x \in \langle f, e \rangle : N(x) &= -gL \\
 N(f) &= -qL \\
 N(e) &= -gL
 \end{aligned}$$



průběh posouvajících sil

$$\begin{aligned}
 x \in \langle h, g \rangle : T(x) &= -qx \\
 T(h) &= 0 \\
 T(g) &= -qL \\
 x \in \langle g, h \rangle : T(x) &= -G_y = qL \\
 T(g) &= qL \\
 T(f) &= qL \\
 x \in \langle e, f \rangle : T(x) &= -E_y = -qL \frac{1}{2} \\
 T(e) &= -\frac{1}{2}qL \\
 T(f) &= -\frac{1}{2}qL
 \end{aligned}$$



průběh ohybových momentů

$$\begin{aligned}
 x \in \langle h, g \rangle : M(x) &= \frac{1}{2}qx^2 \\
 M(h) &= 0 \\
 M(g) &= \frac{1}{2}qL^2 \\
 x \in \langle g, f \rangle : M(x) &= M(g) + G_y x = \frac{1}{2}qL^2 - qLx \\
 M(g) &= \frac{1}{2}qL^2 \\
 M(f) &= \frac{1}{2}qL^2 - qL^2 = -\frac{1}{2}qL^2 \\
 x \in \langle d, c \rangle : M(x) &= -E_y x = -\frac{1}{2}qLx \\
 M(e) &= 0 \\
 M(f) &= -\frac{1}{2}qL^2
 \end{aligned}$$